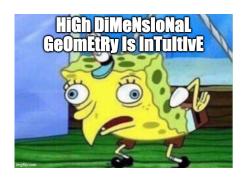
Foundations of Data Science Avrim Blum, John Hopcroft, and Ravindran Kannan

Christian Howard

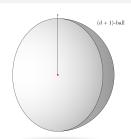
June 13, 2020

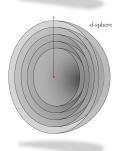
Main Message



- Things get weird in high dimensions
 - ▶ Volume and surface area of d-ball goes to 0 as $d \to \infty$
 - ► Majority of volume of *d*-ball is near surface and along "equators" of the ball
 - ► Any two random points in *d*-ball are (almost) orthogonal

Volume of Unit Ball - Section 2.4.1





- $V_d(r) := \text{volume of } d\text{-ball with radius } r$
 - $V_d(r) = r^d V_d(1)$
- $S_d(r)$:= area of d-sphere (surface area of (d+1)-ball) with radius r
 - $S_d(r) = r^d S_d(1)$
- View $V_d(r)$ as union of (d-1)-spheres with radii from 0 to r
 - $V_d(r) = \int_0^r S_{d-1}(x) dx$
 - Notice that $\frac{dV_d}{dr}(r) = S_{d-1}(r)$

Volume of Unit Ball - Section 2.4.1

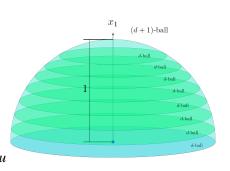
- Since $V_d(r) = r^d V_d(1)$, need to just find $V_d(1)$
- $V_{d+1}(1)$ can be viewed as union of *d*-balls with radii between 0 and 1

$$V_{d+1}(1) \stackrel{1}{=} 2 \int_0^1 V_d((1-x^2)^{\frac{1}{2}}) dx$$

$$\stackrel{2}{=} 2V_d(1) \int_0^1 (1-x^2)^{\frac{d}{2}} dx$$

$$\stackrel{3}{=} V_d(1) \int_0^1 u^{-\frac{1}{2}} (1-u)^{\frac{d}{2}} du$$

$$\stackrel{4}{=} V_d(1) B\left(\frac{1}{2}, \frac{d}{2} + 1\right)$$



The Beta and Gamma functions

Gamma Function Facts

$$\bullet$$
 $\Gamma(s) := \int_0^\infty x^{s-1} e^{-x} dx$

•
$$\Gamma(s+1) = s\Gamma(s)$$

•
$$\Gamma(s+1) = s!$$
 for $s \in \mathbb{N}$

•
$$\Gamma\left(\frac{1}{2}\right) = \sqrt{\pi}$$

$$\Gamma\left(\frac{3}{2}\right) = \frac{\sqrt{\pi}}{2}$$

Beta Function Facts

•
$$B(s,t) := \int_0^1 x^{s-1} (1-x)^{t-1} dx$$

$$B(s,t) = B(t,s)$$

•
$$B(s,t) = \frac{\Gamma(s)\Gamma(t)}{\Gamma(s+t)}$$

Volume of Unit Ball - Section 2.4.1

By unrolling the recursion for $V_d(1)$, and recognizing the base case $V_0(1) = 1$, we have

$$V_{d}(1) \stackrel{1}{=} V_{d-1}(1)B\left(\frac{1}{2}, \frac{d-1}{2} + 1\right)$$

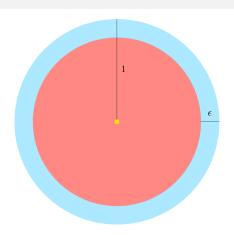
$$\stackrel{2}{=} V_{0}(1) \prod_{j=0}^{d-1} B\left(\frac{1}{2}, \frac{j}{2} + 1\right)$$

$$\stackrel{3}{=} V_{0}(1)\Gamma(1/2)^{d} \frac{\Gamma(1)}{\Gamma(\frac{3}{2})} \frac{\Gamma(\frac{3}{2})}{\Gamma(2)} \cdots \frac{\Gamma(\frac{d+1}{2})}{\Gamma(\frac{d}{2} + 1)}$$

$$\stackrel{4}{=} \frac{2\pi^{\frac{d}{2}}}{d\Gamma(\frac{d}{2})}$$

Implies that
$$V_d(r) = \frac{2\pi^{\frac{d}{2}}r^d}{d\Gamma(\frac{d}{2})}$$
 and $S_d(r) = \frac{dV_{d+1}}{dr}(r) = \frac{2\pi^{\frac{d+1}{2}}r^d}{\Gamma(\frac{d+1}{2})}$.

Volume Near the Surface - Section 2.3



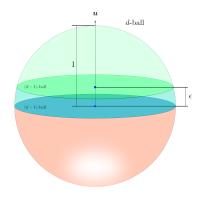
Define a unit *d*-ball with radius *r* as $B_d(r)$. For any fixed $\epsilon > 0$, we have

$$\Pr\{\|\boldsymbol{p}\| < 1 - \epsilon\} = \frac{\text{vol}(B_d(1 - \epsilon))}{\text{vol}(B_d(1))} = \frac{V_d(1 - \epsilon)}{V_d(1)} = \frac{V_d(1)(1 - \epsilon)^d}{V_d(1)} \le e^{-\epsilon d}$$

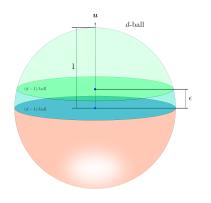
 For any fixed unit vector u, most of the volume in a d-ball is made of points p where

$$|\boldsymbol{u}\cdot\boldsymbol{p}|=O\left(1/\sqrt{d}\right)$$

• Implies most points in the ball are nearly orthogonal to \boldsymbol{u}



- Fix some arbitrary unit vector *u*
- $H \subseteq B_d(1)$ such that any $p \in H$ satisfies $|\mathbf{u} \cdot \mathbf{p}| \ge \epsilon$ for some fixed $\epsilon > 0$.
- Consider finding $\Pr\{|\boldsymbol{u}\cdot\boldsymbol{p}| \geq \epsilon\}$ for a point \boldsymbol{p} uniformly at random chosen from $B_d(1)$



• Geometrically,

$$\Pr\{|\boldsymbol{u}\cdot\boldsymbol{p}| \ge \epsilon\} = \frac{\operatorname{vol}(H)}{\operatorname{vol}(B_d(1))} = \frac{\operatorname{vol}(H)}{V_d(1)}$$

We have that

$$vol(H) = 2V_{d-1}(1) \int_{\epsilon}^{1} (1 - x^2)^{\frac{d-1}{2}} dx$$

We can further obtain that

$$\operatorname{vol}(H) \stackrel{1}{=} 2V_{d-1}(1) \int_{\epsilon}^{1} (1 - x^{2})^{\frac{d-1}{2}} dx$$

$$\stackrel{2}{\leq} 2V_{d-1}(1) \int_{\epsilon}^{1} e^{-\frac{x^{2}(d-1)}{2}} dx \qquad (1 - s \leq e^{-s})$$

$$\stackrel{3}{\leq} 2\frac{V_{d-1}(1)}{\epsilon(d-1)} \int_{\epsilon}^{\infty} (d-1)xe^{-\frac{x^{2}(d-1)}{2}} dx \qquad (\frac{1}{\epsilon} \geq \frac{x}{\epsilon} \geq 1)$$

$$\stackrel{4}{=} \frac{2V_{d-1}(1)}{\epsilon(d-1)} e^{-\frac{\epsilon^{2}(d-1)}{2}}$$

The probability bound is then

$$\Pr\{|\boldsymbol{u}\cdot\boldsymbol{p}| \geq \epsilon\} \stackrel{!}{=} \frac{\operatorname{vol}(H)}{V_d(1)}$$

$$\stackrel{?}{\leq} \frac{2V_{d-1}(1)}{\epsilon(d-1)V_d(1)} e^{-\frac{\epsilon^2(d-1)}{2}}$$

$$\stackrel{3}{=} \frac{2e^{-\frac{\epsilon^2(d-1)}{2}}}{\epsilon(d-1)B\left(\frac{1}{2}, \frac{d-1}{2} + 1\right)}$$

$$\stackrel{4}{=} \frac{2e^{-\frac{a^2}{2}}}{a\sqrt{d-1}B\left(\frac{1}{2}, \frac{d-1}{2} + 1\right)} \qquad (\epsilon = \frac{a}{\sqrt{d-1}})$$

Define $f(d) := \frac{\sqrt{d}}{2}B\left(\frac{1}{2},\frac{d}{2}+1\right)$. Can show that f(d) is monotonically increasing for $d \ge 0$ by taking derivative and seeing that $f'(d) \ge 0$ for $d \ge 0$. Thus for $d \ge 1$, we have that

$$f(d) \stackrel{1}{=} \frac{\sqrt{d}}{2} B\left(\frac{1}{2}, \frac{d}{2} + 1\right)$$

$$\stackrel{2}{=} \frac{1}{2} B\left(\frac{1}{2}, \frac{1}{2} + 1\right)$$

$$\stackrel{3}{=} \frac{\Gamma(1/2)\Gamma(3/2)}{2\Gamma(2)}$$

$$\stackrel{4}{=} \frac{\pi}{4} \qquad (\Gamma\left(\frac{1}{2}\right) = \sqrt{\pi}, \Gamma\left(\frac{3}{2}\right) = \frac{\sqrt{\pi}}{2})$$

Using the previous result, we have that

$$\Pr\left\{|\boldsymbol{u}\cdot\boldsymbol{p}| \ge \frac{a}{\sqrt{d-1}}\right\} \stackrel{1}{\le} \frac{2e^{-\frac{a^2}{2}}}{a\sqrt{d-1}B\left(\frac{1}{2},\frac{d-1}{2}+1\right)} \\ \stackrel{2}{\le} \frac{4}{\pi a}e^{-\frac{a^2}{2}} \\ \stackrel{3}{\le} \frac{4}{\pi}e^{-\frac{a^2}{2}} \qquad (a \ge 1)$$

Implies that for any fixed direction \boldsymbol{u} and with probability at least $1 - \frac{4}{\pi a}e^{-\frac{a^2}{2}}$, we have for a random point \boldsymbol{p} chosen from a d-ball for $d \ge 1$ that $|\boldsymbol{u} \cdot \boldsymbol{p}| \le \frac{a}{\sqrt{d-1}}$.

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Theorem 1 (Properties of randomly sampled points on unit ball)

Suppose you randomly sample n points x_1, x_2, \dots, x_n i.i.d. from a unit d-ball. For some $k \ge 1$ and probability at least $1 - O(1/n^k)$, these points will satisfy both conditions:

- **1** For all i, $||x_i|| \ge 1 \frac{(k+1) \ln n}{d}$ **2** For all $i \ne j$, $|x_i \cdot x_j| \le \frac{\sqrt{2(k+2) \ln n}}{\sqrt{d-1}}$

Proof

For Condition 1, fix some point x_i and define $\mathcal{E}_i^{(1)}$ the error event that $\|x_i\| < 1 - \frac{(k+1)\ln n}{d}$. We know from earlier that $\Pr\{\|x_i\| < 1 - \epsilon\} \le e^{-\epsilon d}$, implying for $\epsilon = \frac{(k+1)\ln n}{d}$ that

$$\Pr\left\{\mathcal{E}_{i}^{(1)}\right\} = \Pr\left\{\|\mathbf{x}_{i}\| < 1 - \frac{(k+1)\ln n}{d}\right\} \le e^{-\frac{(k+1)\ln n}{d}d} = 1/n^{k+1}$$

Then, overall error probability $\Pr\left\{\exists i: \mathcal{E}_i^{(1)}\right\} \leq n \Pr\left\{\mathcal{E}_1^{(1)}\right\} = 1/n^k$.

Proof continued

For Condition 2, fix two points x_i and x_j with i < j and define $\mathcal{E}_{i,j}^{(2)}$ as the error event that $|x_i \cdot x_j| \ge \frac{\sqrt{2(k+2)\ln n}}{\sqrt{d-1}}$. Fix $u = x_i / ||x_i||$ as the direction of interest. We know from earlier for $d \ge 1$ and $\sqrt{2(k+2)\ln n} \ge 1$ that

$$\Pr\left\{\mathcal{E}_{i,j}^{(2)}\right\} \le \Pr\left\{|\boldsymbol{u} \cdot \boldsymbol{x}_j| \ge \frac{\sqrt{2(k+2)\ln n}}{\sqrt{d-1}}\right\} \le \frac{4}{\pi}e^{-\frac{2(k+2)\ln n}{2}} = \frac{4}{\pi n^{(k+2)}}$$

Then, overall error probability $\Pr\left\{\exists i < j: \mathcal{E}_{i,j}^{(2)}\right\} \leq \binom{n}{2} \Pr\left\{\mathcal{E}_{1,2}^{(2)}\right\} \leq \frac{4}{\pi n^k}.$

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Proof continued

By union bound, we have that

$$\Pr \left\{ \text{Condition 1 or 2 unsatisfied} \right\} \le \frac{1}{n^k} + \frac{4}{\pi n^k} = O\left(\frac{1}{n^k}\right)$$

So the probability that Conditions 1 and 2 are **both** satisfied is at least $1 - O(1/n^k)$.



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